

用户使用说明书 User's Instruction Manual



1/8 Scale 4WD Brushless Electric Buggy

Introduction

Thank you for choosing DHK's Optimus! This model is designed in thorough research and assembled with utmost craftmanship. It is easy to drive and it uses quality parts and accessories to achieve best performance. It will bring you a lot of joy and fun when you drive this model.

Before starting to run the model, you are kindly requested to take some time to review this instruction manual for a better operation. This easy to follow instruction manual aims to provide a general guideline for end-users. Kindly note that a good understanding of the model, its relevant parts together with other accessories packed in this consumer box will enable you to have fun in driving. Meanwhile, users are recommended to conduct regular maintenance for a smooth performance. Failure to do so might shorten the lifespan of your model. You are cordially advised that DHK Hobby makes all necessary parts and accessories to support you for any problem during and after your driving.

Before you operate this radio controlled model, you must understand the following:

1.Make sure that all screws and nuts are tightened securely.

2. Make sure that the batteries are fresh or fully charged so the vehiche won't lose control.

3.Do not drive the model in the following places/areas to avoid injury of people and damage to the public property. Drive your model in open areas.

- > On public streets or parks. Cause injury or death of pedestrians, young children, animals and pets.
- > On highways. Cause accidents or damage of the model.
- > In water. Cause damage to electronic components and parts, or direct failure of the model.

4. Check all signals and electronic parts are working properly.

After running, battery, ESC, and motor can be very hot. Make sure not to touch with bare hands.

Warning:

This high performance model can run very fast. It is designed and produced for people of 14+ years of age to operate. Players under that age should be guided by adult supervision. Entry level players should seek guidance and supervision from experienced model players. Players are responsible for any/all accidental occurrences (human or animal injury, damage to property and possessions, breakage of the model itself) due to improper operation of this model.



Model specifications

Overall length	: 19.4" (493.3mm)
Width	: 12.1" (307.7mm)
Height	: 6.76" (171.9mm)
Wheelbase	: 12.98" (330.1mm)
Ground clearance	: 1.36" (34.6mm)
Weight (net)	: 2920g
Front track/rear track	: 10.23" (260.0mm)/10.43" (265.0mm)
Front tyres/rear tyres	: Φ118,45mm/Φ118,45mm
Front wheels/rear wheels	: Φ81,42mm/Φ81,42mm
Gear ratio	: 10.68:1

Articles required to operate the model

8 pcs AA batteries (Ni-Mh or Ni-Cd rechargable batteries, or non-rechargable alkaline batteries) for 2.4GHz transmitter. Please refer to the 2.4GHz transmitter Instruction Manual.



Lipo balance charger (#P109) (for 2S/3S Lipo battery) 1,000mAh output with AC input.



2 Channel 2.4GHz radio system

Optimus comes with a full function 2 channel 2.4GHz radio transmitter and receiver. Please refer to the 2.4GHz User's Instructions Manual for detail.

Brushless electronic speed control (ESC)

Optimus comes with 60A brushless electronic speed controller. Please refer to the instructions manual of the ESC for detail.

Brushless electric motor

Motor KV(RPM)	: 2260
Power	: 7.4V
Empty load current	: 3.2A
Resistance(Ω)	: 17.5-19.2Ω
Length(including motor shaft)	: 75mm
Diameter	: 36mm
Weight	: 291g
Shaft diameter	: 5mm



9kgs Servo

Features	: Metal gears, ball bearings
Working voltage	: 6.0V
Speed (seconds/60°C)	: 0.16sec
Torque	: 9kg/cm (88.3Ncm)
Net weight	: 60g
Size(LxWxH)	: 55x21x43mm

Note:

When the motor temperature is over 120°C(248°F), please add a fan over the motor for better ventilation. Please refer to the parts list for the optional part motor cooling fan (Part#: P101).

Lipo Batteries

This model comes with single 11.1V 3200mAh Lipo battery pack. Handling Lipo batteries should be very careful. Please read the following points with regard to charging and discharging Lipo batteries.

Charging the Lipo battery

Important warnings:

Be sure to follow these important warnings regarding the charging of Lipo batteries.

> Never leave a Lipo battery unattended at any time while being charged.

> Never charge a Lipo battery while it's inside the model. A hot pack could ignite wood, foam, plastic, etc.

> Never charge Lipo battery with Ni-Mh or Ni-Cd peak charger. Only use a charger designed specifically for Lipo batteries which can apply the constant current/constant voltage charge technique.

> Never charge Lipo battery at currents greater than the "1C" rating of the battery.

> Never allow Lipo cells to overheat at any time. Cells which exceed 60°C (140°F) during charge can and usually will become damaged physically and possibly catch fire. Always inspect a battery which has previously overheated and do not re-use if you suspect it has been damaged in any way.

> Always discontinue charging a Lipo immediately if at any time you witness smoke or see the battery starting to swell up. This may cause the battery to rupture and/or lead, and the reaction with air may cause the chemicals to ignite, resulting in fire. Disconnect the battery and leave it in a safe fireproof location for approximately 15 minutes.

> Always charge a Lipo battery in a fireproof location, which could be a container made of metal, ceramic tile, or a bucket of sand.

> Never allow a battery's positive and negative leads to accidentally touch each other. This will result in a short circuit and cause permanent damage to your battery and charger.

> Always monitor the battery and charger during the entire charge process. Never leave the battery and charger unattended during charge!

> Never continue to charge the Lipo batteries if the charger fails to recognize full charge. Overheating or swelling of the Lipo cells is an indication that a problem exists and the batteries should be disconnected from the charger immediately and placed in a fireproof location.

Discharging the Lipo battery

> Never leave a Lipo battery unattended at any time while being discharged.

> Always discharge Lipo batteries in a fireproof location, which could be a container made of metal or on ceramic tile.

> Always connect the battery's lead marked "Discharge" or "TO ESC" to the electronic speed controller. Never attempt to connect the battery's "CHARGE" lead to the ESC.

> It is strongly recommended to use an ESC which is designed to handle the low voltage cutoff points or Lipo batteries (Always follow the instructions provided with the ESC for proper operation). Discharging Lipo batteries below 2.5V per cell (Norm is 3.7V per cell, at 4.2V once fully charged) can cause permanent damage and limit the number of times the battery can effectively be used again.

> Never discharge Lipo batteries at currents which exceed the discharge current rating of the battery as this can often cause a cell to overheat. Do not allow a Lipo cell to exceed 60°C (140°F) during discharge.

Caution!

Cells may be hot. Do not allow the battery's internal electrolyte to get in the eyes or on skin. Wash affected areas with soap and water immediately if they come in contact with the electrolyte. If electrolyte makes contact with the eyes, flush with large amounts of water for 15 minutes and seek medical attention immediately.

Carefully inspect Lipo batteries which have been involved in a crash for even the smallest of cracks, splits, punctures or damage to the wiring and connectors.

Disposal of Lipo batteries

Unlike Ni-Cd batteries, Lithium-polymer batteries are environmentally friendly. For safety reasons, it's best that Lipo cells be fully discharged before disposal (however, if physically damaged it is not recommended to discharge Lipo cells before disposal). The batteries must also be cool before proceeding with disposal instructions. To dispose of Lipo cells and packs:

> If any Lipo cell in the pack has been physically damaged, resulting in a swollen cell or a split or tear in a cell's foil covering, do not discharge the battery.

> Place the Lipo battery in a fireproof container or bucket of sand.

> Connect the battery to a Lipo discharger. Set the discharge cutoff voltage to the lowest possible value. Set the discharge current to a C/10 value, with "C" being the capacity rating of the pack.

> Discharge the battery until its voltage reaches 1.0V per cell or lower. For resistive load type dischargers, discharge the battery for up to 24 hours.

> Submerse the battery into bucket or tub of salt water. This container should have a lid, but it does not need to be air-tight. Perhaps a bucket or tub containing 3 to 5 gallons of cold water, and mix in 1/2 cup of salt per gallon of water. Drop the battery into the salt water. All the battery to remain in the tub of salt water for at least 2 weeks.

> Remove the Lipo battery from the salt water and place it in the normal trash.

Terminology

Electronic speed control (ESC)

An electronic circuit with the purpose to vary an electric motor's speed, its direction and possibly also to act as a dynamic brake. ESCs are often used on electrically-powered radio controlled models.

An ESC can be a stand-alone unit which plugs into the receiver's throttle control channel or incorporated into the receiver itself, as is the case in most toy-grade R/C vehicles. Some R/C manufacturers that install proprietary hobby-grade electronics in their entry-level vehicles, vessels or aircraft use onboard electronics that combine the two on a single circuit board.

Brushless DC motors (BLDC motors, BL motors)

Also known as electronically commutated motors (ECMs, EC motors). BLDC motors are synchronous electric motors powered by direct-current (DC) electricity and having electronic commutation systems, rather than mechanical commutators and brushes. The current-to-torque and voltage-to-speed relationships of BLDC motors are linear.

BLDC motors may be described as stepper motors, with fixed permanent magnets and possibly more poles on the rotor than the stator, or reluctance motors. The latter may be without permanent magnets, just poles that are induced on the rotor then pulled into alignment by timed stator windings. However, the term stepper motor tends to be used for motors that are designed specifically to be operated in a mode where they are frequently stopped with the rotor in a defined angular position.

RC servos

Servos are hobbyist remote control devices typically employed in radio-controlled models, where they are used to provide actuation for various mechanical systems such as the steering of a car, the control surfaces on a plane, or the rudder of a boat.

Due to their affordability, reliability, and simplicity of control by microprocessors, RC servos are often used in small-scale robotics applications.

RC servos are composed of an electric motor mechanically linked to a potentiometer. A standard RC receiver sends Pulse-width modulation (PWM) signals to the servo. The electronics inside the servo translate the width of the pulse into a position. When the servo is commanded to rotate, the motor is powered until the potentiometer reaches the value corresponding to the commanded position.

RC servos use a three-pin 0.1" spacing jack (female) which mates to standard 0.025" square pins (which should be gold-plated, incidentally). The most common order is Signal, +voltage, ground. The standard voltage is 6VDC, however 4.8V and 12V has also been seen for a few servos. The control signal is a digital PWM signal with a 50Hz frame rate. Within each 20ms timeframe, an active-high digital pulse controls the position. The pulse nominally ranges from 1.0ms to 2.0ms with 1.5ms always being center of range. Pulse widths outside this range can be used for "overtravel" -moving the servo beyond its normal range. This PWM signal is sometimes (incorrectly) called Pulse Position Modulation (PPM).

The servo is controlled by three wires: ground, power, and control. The servo will move based on the pulses sent over the control wire, which set the angle of the actuator arm. The servo expects a pulse every 20 ms in order to gain correct information about the angle. The width of the servo pulse dictates the range of the servo's angular motion.

A servo pulse of 1.5 ms width will typically set the servo to its "neutral" position or 45°, a pulse of 1.25 ms could set it to 0° and a pulse of 1.75 ms to 90°. The physical limits and timings of the servo hardware varies between brands and models, but a general servo's angular motion will travel somewhere in the range of 90° - 120° and the neutral position is almost always at 1.5 ms. This is the "standard pulse servo mode" used by all hobby analog servos.

A hobby digital servo is controlled by the same "standard pulse servo mode" pulses as an analog servo. Some hobby digital servos can be set to another mode that allows a robot controller to read back the actual position of the servo shaft. Some hobby digital servos can optionally be set to another mode and "programmed", so it has the desired PID controller characteristics when it is later driven by a standard RC receiver.

RC servos are usually powered by the receiver which in turn is powered by battery packs or an Electronic speed controller (ESC) with an integrated or a separate Battery eliminator circuit (BEC). Common battery packs are either NiCd, NiMH or Lithium-ion polymer battery (LiPo) type. Voltage ratings vary, but most receivers are operated at 5V or 6V.

Parts List

Number	Desc	Number	Desc	
8381-100	Assembly of diff gear box	8381-602	Buffer bushing/adjustment ring	
8381-101	381-101 Diff set		Buffer spring (4 pcs)	
8381-102	Diff outdrive/pins (dia 2*10mm)	8381-604	Buffer sus arm-upper/lower/steering sus arm	
8381-103	Pins(dia 2*10mm) (16 pcs)	8381-605	B head screw-coarse thread(BB3*12mm) (16 pcs)	
8381-104	Elathead screw-coarse thread(KB2 6*10mm) (16	8381-606	Screw bushing (16 pcs)	
	pcs)	8381-601	Steering plate	
8381-105	Crown gear-41T (large)/pinion gear-11T (small)	8381-608	Shaft (2 ncs)	
8381-106	Diff case set/diff case cover/diff gasket	8381-670	Assembly of steering linkage (2 pcs)	
8381-107	Washer-A/washer-B (8 pcs each)	8381-671	Steering linkage (2 pcs)	
8381-108	Gear-18T (2 pcs)/gear-12T (4 pcs)	8381 672	Diastic rod and (8 pcs)	
8381-100	$O \operatorname{Ring}(\operatorname{dia} 8 \operatorname{mm} * \operatorname{dia} 2 \operatorname{mm}) (16 \operatorname{ncs})$	0201 672	Pauble way hall and (9 pcs)	
8381-110	Ball bearing(dia 10mm * dia 15*4mm) (2 pcs)	0301-023		
8381-111	Diff nins(dia $4*25$ 8mm) (4 ncs)	0301-701	Dependence of the second secon	
8381-112	Assembly of the ninion dear	8381-702	B head screw-coarse thread(BB3*14mm) (16 pcs)	
9391 112	Elathoad scrow(KM2 6X6mm) (16 pcs)	8381-703	B head screw-coarse thread(BB3*10mm) (16 pcs)	
0301-113	Pall booring(dia 2mm * dia14*4mm) (2 pag)	8381-704	Sus.arm long axie/short axie (2 sets)	
0301-114	Dine (dia 0*0mm) (40 mm)	8381-705	E-Clip(dia 2^0.4mm) (16 pcs)	
8381-115	Pins(dia 2°8mm) (16 pcs)	8381-706	Lower sus.arm-front (2 pcs)	
8381-110	Prinon gear outdrive/pins(dia 2*8mm)	8381-707	Drive shaft set/revolving shaft (2 sets)	
8381-117	Ball bearing(dia 5 mm ^ dia 11^4mm) (2 pcs)	8381-708	Wheel axle (2 pcs)	
8381-118	Diff gear box-F/R	8381-709	Steering arm (2 pcs)	
8381-119	B head screw-coarse thread(BB3*16mm) (16 pcs)	8381-710	Ball bearing(dia 5mm * dia 10*4mm) (2 pcs)	
8381-200	Central diff gear box(complete)	8381-711	Hex adapter/nut-M12	
8381-201	Central diff set	8381-712	Pins(dia 2*16mm) (16 pcs)	
8381-202	Center diff pins/pins(dia 2*10mm)	8381-713	B head screw(BM3*12mm) (16 pcs)	
8381-203	Spur gear-43T(plastic) (2 pcs)	8381-714	C-hub (2 pcs)	
8381-204	Lock nut (M4*4mm) (16 pcs)	8381-715	B head screw(BM3*20mm) (16 pcs)	
8381-205	Center diff outdrive/lock nut(M4*4mm)	8381-716	Lock nut(M4*10mm) (16 pcs)	
8381-206	Center diff gear box/center diff gear box plate	8381-717	Brace (2 pcs)	
8381-207	B head screw-coarse thread(BB3*20mm) (16 pcs)	8381-718	Pivot ball mount (4 pcs)	
8381-300	Shock absorber complete (2 pcs)	8381-719	Upper sus.arm shaft (4 pcs)	
8381-301	Shock cap (2 pcs)	8381-720	Front bumper/upper sus.arm mount-front	
8381-302	Shock connecting rod-upper/lower/O ring (dia	8381-721	Lower sus.arm plate-front	
	12mm * dia 2mm)	8381-726	B head screw-coares thread(BB3*18mm) (16 pcs)	
8381-303	Shock adjust ring /O ring (dia 18.5mm * dia 1.5mm)	8383-001	Tire complete (black rims) (2 pcs)	
	(2 pcs)	8381-801	Lower sus.arm-rear (2 pcs)	
8381-304	Shock body (2 pcs)	8381-802	Rear hub-L/F	
8381-305	Shock ball (8 pcs)	8381-803	B head screw(BM3*18mm) (16 pcs)	
8381-306	M3 nylon nut (8 pcs)	8381-804	Wing mount/wing brace-L/R	
8381-307	Lower shock mount/piston/O ring(dia 13mm * dia	8381-805	B head screw(BM3*10mm) (16 pcs)	
	[1.5mm)	8381-806	Rear wing rod-long/short	
8381-308	O ring (16 pcs)	8381-807	Pin-A(dia 1.5mm) (16 pcs)	
8381-309	Shock shaft (4 pcs)	8383-002	Rear wing (black)	
8381-310	Shock spring (4 pcs)	8381-9M1	Motor mount-Upper/Lower	
8381-400	Anti-roll bar assembly	8381-9M2	Motor gear-15T/Lock nut(M4*4)	
8381-40L	Assembly of anti-roll bar linkage-Left	8381-950	Assembly of 9kgs_servo (with servo horns)	
8381-40R	Assembly of anti-roll bar linkage-Right	8381-951	Servo mount	
8381-401	Anti-roll bar rod end (8 pcs)	8381-052	Servo steering plate (2 pcs)	
8381-402	Anti-roll bar linkage (4 pcs)	8381-053	B bead screw/(BM3*6mm) (16 pcs)	
8381-403	Anti-roll bar pivot ball-upper/lower (4 sets)	8381 070	Assembly of steering tie red	
8381-404	Lock nut(M3*3mm) (8 pcs)	0301-920	Assembly of steering tie rod	
8381-405	Anti-roll bar(dia 2.2mm) (2 pcs)	0001-921	Chassie	
8381-50L	Assembly of upper sus.arm-Left	0303-003		
8381-50R	Assembly of upper sus arm-Right	0000 000		
8381-501	Upper sus.arm ball (4 pcs)	8382-003	Battery mount-A/B	
8381-502	Upper sus.arm/rod end (2 sets)	8381-004	Upper deck mount-F/R	
8381-503	Upper sus.arm linkage (2 pcs)			
8383-600	Assembly of buffer set			
8381-601	Brass washer (4 pcs)			

Number	Desc
8381-005	Central drive shaft-A
8381-006	Central drive shaft-B
8381-007	Receiver cover-upper/lower
8381-008	Antenna tube (3 pcs)
8381-009	Pin-B(dia 1.2mm) (16 pcs)
8381-010	Screw washer
8381-011	Flathead screw(KM3X10mm) (16 pcs)
8381-012	Flathead screw-coarse thread(KB3*10mm) (16 pcs)
8381-013	Flathead screw-coarse thread(KB3*12mm) (16 pcs)
8381-014	Flathead screw (KM3*5mm) (16 pcs)
8381-015	Flathead screw(KM3X18mm) (16 pcs)
8381-016	Upper deck-A
8381-017	Upper deck-B
8381-018	Body post-F/R/wire mount-A
8383-003	Battery cover
8381-020	Hex driver H17
8381-021	Painted body
H104	Brushless ESC (60A)
H105	Brushless motor (KV:2260)
H106	LiPo battery (11.1V, 20C, 3200mAh)
D302	2 channel 2.4GHz transmitter complete (with receiver)
D302H	2 channel 2.4GHz LCD transmitter w/ receiver (Optional)
D302R	4 channel 2.4GHz receiver













8381-201 Central diff set

(complete)

8381-202 Center diff pins/pins (dia 2*10mm)













Note:

Images are for easy track of the parts, they don't alway srepresent the actual quantity of parts packs.

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